

Regression:  $N$ : data-size  $D$ : dim (features)  $D_{par}$ : Model param. with offset  $w_0$

relates  $x_n$  to  $y_n$ . Regression function:  $y_n \approx f(x_n) = f(w; x_n) \rightarrow 2$  goals: Prediction, Interpretation

Linear Regression: Univariate:  $y_n \approx f(x_n) := w_0 + w_1 x_n$

Multivariate:  $y_n \approx f(x_n) := w_0 + w_1 x_{n1} + \dots + w_n x_{nd} = w_0 + x_n^T \tilde{w} = \tilde{x}_n^T \tilde{w}$   
Note: If  $D > N$ , we say the model is overparametrized  $\Rightarrow$  Solution: Regularization

Cost function:  $J(w) = \frac{1}{N} \sum_{n=1}^N \text{loss}(e_n)$ ,  $e_n = y_n - f(w; x_n)$  2 desirable properties:

1) symmetric around 0 2) Penalize large and huge mistakes the same (outliers robust)

MSE(w) :=  $\frac{1}{N} \sum_{n=1}^N (y_n - f(w; x_n))^2$  MAE(w) :=  $\frac{1}{N} \sum_{n=1}^N |y_n - f(w; x_n)|$  more robust to outliers than MSE

Convexity: A function  $h(w)$  with  $w \in \mathbb{R}^D$  is convex if for any  $u, v \in \mathbb{R}^D$  and any  $0 \leq \lambda \leq 1$ :  $h(\lambda u + (1-\lambda)v) \leq \lambda h(u) + (1-\lambda)h(v)$  desirable computational property

A strict convex function has a unique global min. For convex functions, every local min is a global min

Sum of convex functions are convex.  $f: \mathbb{R}^D \rightarrow \mathbb{R}$  convex iff  $\nabla^2 f = PSD$

Local opt:  $L(w) \leq L(w')$   $\forall w$  with  $\|w - w'\| < \epsilon$  Global:  $L(w^*) \leq L(w)$   $\forall w \in \mathbb{R}^D$

LS: Solving Lin Reg with MSE analytically. 2 steps for global opt. 1) Show convexity 2)  $\nabla J(w) = 0$

Normal eq:  $J(w) = \frac{1}{2N} \sum_{n=1}^N (y_n - x_n^T w)^2 = \frac{1}{2N} e^T e$  with  $e = Y - Xw$

Cost fct is convex bc it's combination of convex fcts (Cost):  $\Theta(N \cdot D)$

$\nabla J(w) = -\frac{1}{N} X^T e \stackrel{!}{=} 0 \Rightarrow X^T X w = X^T y \Rightarrow w^* = (X^T X)^{-1} X^T y$  iff Gram matrix  $X^T X \in \mathbb{R}^{D \times D}$  is invertible (if  $\text{rank}(X) = D$ ) Prediction on unseen data:  $\hat{y}_m := x_m^T w^* = x_m^T (X^T X)^{-1} X^T y$ . If  $D > N$ :  $\text{rank}(X) < D$ . If  $D \leq N$ , but some col  $x_i$  are (nearby) collinear: ill-cond.  $\Rightarrow$  Solution: Linear Solver;  $X^T X w = X^T y$

Underfitting: can't find fit, too limited. Overfitting: Fits noise too, too rich

Augment linear models:  $y_n \approx w_0 + w_1 x_n + w_2 x_n^2 + \dots + w_{D+1} x_n^D = \phi(x_n)^T w$

Avoid overfit: Increase  $N$ , keep  $M$  fixed (old data, same model complexity)

MLE: Gaussian RV in  $\mathbb{R}^D$ :  $N(y | \mu, \Sigma) = \frac{1}{(2\pi)^{D/2} |\Sigma|^{1/2}} \exp[-0.5(y-\mu)^T \Sigma^{-1}(y-\mu)]$  ( $\Sigma$  PSD)

Note: 2 RV indep when  $\text{cov}(X,Y) = 0$  in  $\mathbb{R}$ :  $P(y | \mu, \sigma^2) = N(y | \mu, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp[-(y-\mu)^2 / 2\sigma^2]$

Probabilistic model for LS: assume data  $y_n = x_n^T w + \epsilon_n$  with  $\epsilon_n \sim N(0, \sigma^2)$

Likelihood:  $p(y | X, w) = \prod_{n=1}^N p(y_n | x_n, w) = \prod_{n=1}^N N(y_n | x_n^T w, \sigma^2)$  Goal: to max it, and it's equivalent as min loss

Log:  $\mathcal{L}_L(w) := \log p(y | X, w) = -\frac{1}{2\sigma^2} \sum_{n=1}^N (y_n - x_n^T w)^2 + \text{const.}$

$\arg \min_w \mathcal{L}_{MSE}(w) = \arg \max_w \mathcal{L}_L(w)$  MLE can also be interpreted as finding the model under which the observed data is most likely to have been generated from (probabilistically)

Properties: MLE is a sample approximation to the expected log-likelihood:  $\mathcal{L}_L(w) \approx E_{y|x}[\log P(y|x,w)]$

MLE is consistent, i.e., it will give us the correct model assuming that we have a sufficient amount of data.

Worse  $\rightarrow$  Worse. MLE is efficient, i.e. it achieves the Cramer-Rao lower bound

Replace Gaussian with Laplace:  $P(y_n | x_n, w) = (2b)^{-1} \exp[-\frac{1}{b} |y_n - x_n^T w|]$

Generalization: Data Model: unknown distrib  $D$  with range  $X \times Y$

Datasets:  $S = \{x_n, y_n\}_{n=1}^N \sim D$  (iid learning algo:  $A(S) = f_S$  (output) ( $S$ : input))

Expect. error:  $L_D(f) = E_{(x,y) \sim S}[l(f(x), y)]$  But  $D$  is unknown Empirical error:  $L_N(f) := \frac{1}{N} \sum_{n=1}^N l(f(x_n), y_n)$

LS(f) =  $\frac{1}{N} \sum_{(x,y) \in S} l(y_n, f(x_n))$  Training error:  $L_S(f) = \frac{1}{N} \sum_{(x,y) \in S} l(y_n, f_S(x_n))$  but could diverge from  $L_D$  bc of overfitting

Split data (test error):  $L_{S_{test}}(f_{S_{train}}) = \frac{1}{|S_{test}|} \sum_{(x,y) \in S_{test}} l(y_n, f_{S_{train}}(x_n)) \approx L_D(f_{S_{train}})$

Generalization error:  $P[l(L_D(f) - L_{S_{test}}(f)) \geq \epsilon] \leq \frac{e^{-2N\epsilon^2}}{2N\epsilon^2}$  Error decreases as  $N$  or test points

Hoeffding's:  $P[l(\frac{1}{N} \sum_{n=1}^N \Theta_n - E(\Theta)) \geq \epsilon] \leq 2e^{-2N\epsilon^2}$  with  $\Theta = l(y, f(x))$

Model Selection: Split data, train  $K$  times for each value, compute error.

Bound:  $P[\max_k |L_D(f_k) - L_{S_{test}}(f_k)| \geq \epsilon] \leq \frac{e^{-2N\epsilon^2}}{2N\epsilon^2}$  Same  $\Theta$

Let  $K^* = \arg \min_k L_D(f_k) \Rightarrow P[L_D(f_{K^*}) \geq L_D(f_k^*) + 2\sqrt{\frac{(b-a)^2 \ln(2NKS)}{2N\epsilon^2}}] \leq \delta$

$K$ -fold Cross-Validation: 1. Randomly partition data into  $K$  groups. 2. Train  $K$  times, leaving 1 group for test and  $K-1$  for train. 3. Average  $K$  results  $\rightarrow$  unbiased estimate of the gen. error and its var.

Logistic reg: model probab  $\xi_0, \xi_1$   $\sigma(w) = \frac{e^w}{1+e^w}$ ,  $1-\sigma(w) = \frac{e^{-w}}{1+e^{-w}}$

$\sigma'(w) = \sigma(w)(1-\sigma(w))$ ,  $P(x) = \sigma(x^T w)$ ,  $P(x) = 1 - P(x)$  if  $P(x) \geq \frac{1}{2} \rightarrow$  Class 1

MLE: assume  $X \perp w$ :  $\mathcal{L}(w) \propto \prod_{n=1}^N \sigma(w^T x_n)^{y_n} (1 - \sigma(w^T x_n))^{1-y_n}$  LL:  $w_* = \arg \min L(w) \rightarrow$

$\frac{1}{N} \sum_{n=1}^N -y_n w^T x_n + \log(1 + e^{w^T x_n})$  Note: if  $\xi_0, \xi_1$ :  $\ell(y, g(x)) = -y g(x) + \log(1 + \exp(g(x)))$  if  $\xi = 1, \xi = 0$

$\log(1 + \exp(-y g(x))) \Rightarrow \nabla L(w) = \frac{1}{N} \sum_{n=1}^N (\sigma(x_n^T w) - y_n) x_n = \frac{1}{N} \sum_{n=1}^N (\sigma(x_n^T w) - y_n) x_n$  No CS solution but convex!  $\nabla L(w)$  Slow  $\Theta(N)$  Sub: fast but converges slow

Newton's:  $L(w) \sim L(w_0) + \nabla L(w_0)^T (w - w_0) + \frac{1}{2} (w - w_0)^T \nabla^2 L(w_0) (w - w_0) \rightarrow$

$w_{t+1} = w_t - \gamma_t \nabla^2 L(w_t)^{-1} \nabla L(w_t) \rightarrow$  intensive! Regularized: issue if data

lin separable  $\Rightarrow \frac{1}{N} \sum_{n=1}^N -y_n w^T x_n + \log(1 + e^{w^T x_n}) + \frac{\lambda}{2} \|w\|_2^2$

Optimization:  $w^* = \arg \min_w J(w)$  s.t.  $w \in \mathbb{R}^D$  but very sensitive to ill-conditioning  $\rightarrow$  Solution: normalize

Smooth: 1) Gridsearch: Go the lowest loss over all  $w$ . Brute-force | exponential complexity | No guarantee to find an optimum

2) Gradient descent: A gradient (at a point) is the slope of the tangent to the function (at that point). It points to the direction of largest increase of the function.

Vector:  $\nabla L(w) = \begin{bmatrix} \frac{\partial L(w)}{\partial w_1} \\ \dots \\ \frac{\partial L(w)}{\partial w_D} \end{bmatrix} \in \mathbb{R}^D$  update rule:  $w^{(t+1)} = w^{(t)} - \gamma \nabla L(w^{(t)})$   $\gamma$  is the step-size or LR. Popular:  $\gamma = \frac{e^2}{N}$   $\rightarrow$  smaller and smaller...  $\rho \nabla L = \frac{1}{2N} \sum_{n=1}^N (-2(y_n - w_0)) = w_0 - \bar{y} \stackrel{!}{=} 0$

Example: GD for 1-param and MSE:  $w_0^{(t+1)} := (1-\gamma)w_0^{(t)} + \gamma \bar{y}$  (converges for  $\gamma \in (0, 2)$ )

GD for linear MSE:  $y = \begin{bmatrix} y_1 \\ \vdots \\ y_N \end{bmatrix}$ ,  $X = \begin{bmatrix} x_{11} & \dots & x_{1D} \\ \vdots & & \vdots \\ x_{N1} & \dots & x_{ND} \end{bmatrix}$ ,  $e = Y - Xw \rightarrow J(w) = \frac{1}{2N} \sum_{n=1}^N (y_n - x_n^T w)^2 = \frac{1}{2N} e^T e$  For MAE:  $\nabla J(w) = -\frac{1}{N} \sum_{n=1}^N \text{sign}(e_n)$

$\nabla J(w) = \frac{1}{N} \sum_{n=1}^N x_n^T e$  Cost of GD per step:  $\Theta(N \cdot D)$

3) SGB: 1) Take 1 random  $n$  2)  $w^{(t+1)} = w^{(t)} - \gamma \nabla L_n(w^{(t)})$  Cheap and unbiased estimate of the gradient:  $E[\nabla L_n(w)] = \nabla L(w)$   $E_n[\nabla L_n(w)] = \sum_{n=1}^N \frac{1}{N} \nabla L_n(w)$  Cost of SGB per step  $\Theta(D)$

4) Mini-batch SGB:  $w^{(t+1)} := w^{(t)} - \gamma g$  with  $g = \frac{1}{|B|} \sum_{n \in B} \nabla L_n(w^{(t)})$ , where  $B$  is a subset.  $\rightarrow B=1$ : classic SGB  $B=N$ : classic GB  $\rightarrow$  easily parallelized

4.1) SGB with momentum:  $w^{(t+1)} := w^{(t)} - \gamma m^{(t+1)}$  with  $m^{(t+1)} := \beta_1 m^{(t)} + (1-\beta_1)g$  faster forgetting of older weights

4.2) ADAM:  $w_i^{(t+1)} := w_i^{(t)} - \frac{\gamma}{\sqrt{v_i^{(t+1)}}} m_i^{(t+1)} \forall i$  with  $m^{(t+1)} := \beta_1 m^{(t)} + (1-\beta_1)g$   $v_i^{(t+1)} := \beta_2 v_i^{(t)} + (1-\beta_2)(g_i)^2 \forall i$  is a momentum variant of Adagrad

4.3) Sign-SGB:  $w_i^{(t+1)} := w_i^{(t)} - \gamma \text{sign}(g_i) \forall i$  only use the sign (one bit) of each gradient entry  $\rightarrow$  communication efficient for distributed training (but convergence issue)

Non-smooth: Vector where function is above is a subgradient. if  $L$  convex and differentiable:  $g = \nabla L(w)$  Cost of GD per step:  $\Theta(N \cdot D)$

1) Subgradient  $g$ : Vector  $g \in \mathbb{R}^D$  such that  $L(u) \geq L(w) + g^T(u-w) \forall u$  Trick: if  $L(w) = h(q(w))$  with  $h$  non-diff and  $q$  diff, Subg of  $L$  at  $w$  is  $g \in \partial h(q(w)) \cdot \nabla q(w)$  Cost of SGB per step  $\Theta(N)$

2) S(S)GB:  $g$  = subgradient to  $L_n(w)$

Conclusion:  $w$  local min if  $\nabla L(w) = 0$  (critical point) and  $\nabla^2 L(w) > 0$  (positive definite)

Regularization: Penalize complex models via:  $\min_w J(w) + \Omega(w)$  where  $\Omega(w)$  is the regularizer

$L_2$ :  $\Omega(w) = \lambda \|w\|_2^2 = \lambda \sum_{i=1}^D w_i^2$  Ridge:  $L_2 + \text{MSE}$ :  $\min_w \frac{1}{2N} \sum_{n=1}^N (y_n - x_n^T w)^2 + \lambda \|w\|_2^2$   $\lambda$  lifts the EV so EV are at least  $\lambda$

$L_1$ :  $\Omega(w) = \lambda \|w\|_1 = \lambda \sum_{i=1}^D |w_i|$  Lasso:  $L_1 + \text{MSE}$ :  $\min_w \frac{1}{2N} \sum_{n=1}^N (y_n - x_n^T w)^2 + \lambda \|w\|_1$  More powerful. Makes  $w$  sparse  $\rightarrow$  even non-0 components

Note:  $\{w : \|y - Xw\|^2 = \alpha\}$  is an ellipsoid. These are likely to touch a corner of the  $L_1$ -ball  $\rightarrow$  sparsity.

Notes: gradient of  $\|w\|_1^2 = 2w$  Subgradient  $\|w\|_1 = (\text{sign}(w_1), \dots, \text{sign}(w_D))$

Bias-Variance:  $Y = f(x) + \epsilon$ . Expected error:  $E_{(x,y) \sim D}[(Y - f_S(x))^2] \rightarrow$  True at every point:  $L(f_S) = E_{(x,y) \sim D}[(f_S(x) + \epsilon - f_S(x))^2]$

$E_{S \sim \mathcal{D}}[L(f_S)] = E_{S \sim \mathcal{D}}[E_{(x,y) \sim D}[(f_S(x) + \epsilon - f_S(x))^2]] = \text{Var}_{S \sim \mathcal{D}}[E] + (E_{(x,y) \sim D}[f_S(x) - f_S(x)])^2 + E_{S \sim \mathcal{D}}[(E_{(x,y) \sim D}[f_S(x) - f_S(x)])^2]$  (can't go below noise var)

Classification: unlike reg.  $Y \in$  discrete set:  $Y \in \{c_1, \dots, c_K\}$  Binary  $K=2$  Classifier divides space into classes

KNN: Pros  $\nsubseteq$  No opt; easy, good for low dim; Cons  $\nsubseteq$  slow, bad for high dim, distance? 3 Max-Margin: HP which

max margin Non-linear classif: feature aug or kernels Binary classif goal:  $\min L_D(f) = E_D(1 \neq f(x)) = P_D(1 \neq f(x))$

Bayes classif:  $f^* = \arg \min_f L_D(f) \rightarrow f^*(x) = \arg \max_{y \in \{1,2\}} P(y=y | x=x)$  unattainable bc  $D$  not known

2 classes of classif algo 1) Non-Param: local Avg (KNN) 2) Param: minERM Problem: Not convex.  $\rightarrow$  Replace  $f$  and  $\ell$  by convex fct.

ERM:  $\min_{f: X \rightarrow Y} ER$  instead True Risk:  $\min_{f: X \rightarrow Y} L_{\text{train}}(f) = \frac{1}{N} \sum_{n=1}^N \ell(f(x_n), y_n) = \frac{1}{N} \sum_{n=1}^N \ell(y_n, f(x_n)) = 0$

Kernel: Ridge:  $\min_w \frac{1}{2N} \sum_{n=1}^N (y_n - w^T x_n)^2 + \frac{\lambda}{2} \|w\|^2 \rightarrow 2$  Solutions  $w_* = \frac{1}{N} (X^T X + \lambda I)^{-1} X^T y$   $w_* = \frac{1}{N} X^T (XX^T + \lambda I)^{-1} y = X^T \alpha$  ( $w^* \in \text{span}(x_1, \dots, x_N)$ )

Representer theorem:  $w_* = \arg \min_w \sum_{n=1}^N \ell(w^T x_n, y_n) + \frac{\lambda}{2} \|w\|^2$  for ANY loss and min (better than LS)  $\Rightarrow w_* = X^T \alpha$   $\rightarrow$  solution in  $\text{span}(x_1, \dots, x_N)$

For ridge ( $\ell = \|y - Xw\|^2$ ): alt formula  $\alpha_* = \arg \min_{\alpha} \frac{1}{2} \alpha^T XX^T \alpha + \lambda \alpha - \frac{1}{2} y^T \alpha$  Kernel matrix:  $K = XX^T = \begin{bmatrix} x_1^T x_1 & \dots & x_1^T x_N \\ \vdots & & \vdots \\ x_N^T x_1 & \dots & x_N^T x_N \end{bmatrix} = (x_i^T x_j)_{i,j \in \{1, \dots, N\}}$   $\in \mathbb{R}^{N \times N}$

With feature map  $\mathbb{R}^D \rightarrow \mathbb{R}^H$ :  $K = \Phi^T \Phi = (\Phi(x_i)^T \Phi(x_j))_{i,j \in \{1, \dots, N\}}$ ,  $i, j \in \mathbb{R}^{N \times N}$  Problem: if  $d \ll D$ ,  $\Phi(x_i)^T \Phi(x_j)$  cost  $\Theta(D) \rightarrow$  expensive!

Kernel Trick:  $K$  fct:  $K(x, x') = \phi(x)^T \phi(x')$   $K(x, x')$  is in the original space! enable computation of classifiers in high-dimensional space without performing computations in the high-dimensional space.

Prediction  $y = \phi(x)^T w_*$  is expensive, so use Rep theorem:  $\phi(x)^T w_* = \phi(x)^T \phi(X) \alpha_* = \sum_{n=1}^N \alpha_n \phi(x)^T \phi(x_n)$  ( $\phi$  feature space)

Kernels: Linear:  $K(x, x') = x^T x'$  Quad:  $K(x, x') = (x^T x')^2$  Poly:  $K(x, x') = (x^T x' + 1)^d$  RBF:  $K(x, x') = \exp(-\gamma \|x - x'\|^2)$   $\cdot K(x, x') = \phi(x)^T \phi(x')$

Create kernels:  $\Theta$  lin Comb:  $K(x, x') = \alpha_1 K_1(x, x') + \beta_2 K_2(x, x')$  for  $\alpha, \beta \geq 0$  Products:  $K(x, x') = K_1(x, x') K_2(x, x')$   $\Rightarrow K(x, x') = e^{2\gamma} K(x, x')$

Mercer's condition: given  $K$ , ensures  $\phi$  if: Kernel fct is symmetric  $K(x, x') = K(x', x)$  Kernel matrix psd  $K = (K(x_i, x_j))_{i,j=1}^N \geq 0 \forall N \geq 0, \forall (x_1, \dots, x_N)$

SVM: Hard SVM: Max-margin separating HP:  $\max_{w,b} \min_{x \in S} w^T x_n$  such that  $\forall n, y_n w^T x_n \geq 1$  Equiv to:  $\max_{w,b} M$  such that  $\forall n, y_n w^T x_n \geq M$   $M = \frac{1}{\|w\|}$

$\Rightarrow \min_{w,b} \frac{1}{2} \|w\|^2$  such that  $\forall n, y_n w^T x_n \geq 1$  Soft-SVM: Not linearly separable!  $\rightarrow$  use slack variable:  $y_n w^T x_n \geq 1 - \xi_n$

$\Rightarrow \min_{w,b} \frac{1}{2} \|w\|^2 + \frac{1}{N} \sum_{n=1}^N \xi_n$  s.t.  $\forall n, y_n w^T x_n \geq 1 - \xi_n$  and  $\xi_n \geq 0$  equiv to:  $\min_{w,b} \frac{1}{2} \|w\|^2 + \frac{1}{N} \sum_{n=1}^N [1 - y_n w^T x_n]_+$   $\rightarrow$  ERM for hinge loss with ridge  $\lambda$

Margin-base losses ( $\eta = yx^T w$ ) MSE( $\eta$ ) =  $(1-\eta)^2$  Hinge( $\eta$ ) =  $[1-\eta]_+$   $\rightarrow$  if  $y_n w^T x_n \geq 1$ , then  $\xi_n = 0$  if  $y_n w^T x_n < 1$ ,  $\xi_n = 1 - y_n w^T x_n$

Opt: Convex duality: How to get  $w$  for Soft-SVM  $\Rightarrow$  Find  $G(w, \alpha)$  so  $\min L(w) = \min_w \max_{\alpha} G(w, \alpha) \geq \max_{\alpha} \min_w G(w, \alpha)$

1)  $[1 - y_n w^T x_n]_+ = \max_{\alpha} \alpha_n (1 - y_n w^T x_n)$   $\rightarrow \min L(w) = \min_w \max_{\alpha \in \{0,1\}^N} \sum_{n=1}^N \alpha_n (1 - y_n w^T x_n) + \frac{\lambda}{2} \|w\|^2$   $\rightarrow$   $G$  convex in  $w$  Concave in  $\alpha$  so we can invert!

2)  $\lambda$  in:  $\nabla_w G(w, \alpha) = -\frac{1}{N} \sum_{n=1}^N \alpha_n y_n x_n + \lambda w = 0 \Rightarrow w(\alpha) = \frac{1}{2N} \sum_{n=1}^N \alpha_n y_n x_n = \frac{1}{2N} X^T Y \alpha$   $\text{diag}(y)$

3) Max:  $\min L(w) = \max_{\alpha \in \{0,1\}^N} \frac{1}{2N} \alpha^T Y X X^T Y \alpha - \frac{\lambda}{2} \alpha^T Y X X^T Y \alpha$   $\alpha_n > 0$  are SV!

$\alpha_n = 0$ :  $X_n \checkmark$  Not margin,  $\alpha_n \in (0,1)$ :  $X_n \checkmark$  margin,  $\alpha_n = 1$ :  $X_n \times$

Ethics: we want knowledge, not stereotypes. ML can't distinguish. data equal discrimination minority: Three fairness criteria: as: can't satisfy them all.

Independence:  $R$  independent of  $A$   $\Rightarrow$  equal acceptance rate

Separation:  $R$  independent of  $A$ , conditional on  $Y \Rightarrow$  equal error rate

Sufficiency:  $Y$  independent of  $A$  conditional on  $R \Rightarrow$  calibration by group

**Linear:**  $L(x) = \theta^T x$  (Learned) **Non-linear:**  $f(x) = \phi(W^T x + b)$  (Learned) **Hidden layers:**  $d$  inputs  $K$  neurons  $W$  matrices  $b$  vectors

Outputs of hidden layer  $l$  given by vector:  $x^{(l)} = f^{(l)}(x^{(l-1)}) := \phi((W^{(l)})^T x^{(l-1)} + b^{(l)})$

**Representation power:** We can use sigmoids to approximate functions. Gross:  $(x_1, x_2) \rightarrow \phi(w_1(x_1 - a_1)) - \phi(w_2(x_2 - b_1)) + \phi(w_3(x_2 - a_2)) - \phi(w_4(x_2 - b_2))$

**USE:**  $\min_{w_1, w_2} \int_{x_1, x_2} (f(x) - g(x))^2 dx \leq \frac{C}{n}$  Also use comb of ReLU as PNL

**SGD:**  $(w_{ij}^{(l)})_{t+1} = (w_{ij}^{(l)})_t - \gamma \frac{\partial \mathcal{L}}{\partial w_{ij}^{(l)}}$   $(b^{(l)})_{t+1} = (b^{(l)})_t - \gamma \frac{\partial \mathcal{L}}{\partial b^{(l)}}$  But doing all chain rules too expensive. **Solution: Backpropagation.**

**NN Params:**  $W^{(l)}: d \times K, W^{(L)}: K \times K$  for  $1 \leq l \leq L, W: K \times K, b^{(l)}: K \times 1$  for  $1 \leq l \leq L, b: K \times 1$   $x^{(l)} = f^{(l)}(x^{(l-1)}) := \phi((W^{(l)})^T x^{(l-1)} + b^{(l)}) = \phi(z^{(l)})$

$\Rightarrow$  Final layer  $y = f^{(L+1)}(x^{(L)}) := (W^{(L+1)})^T x^{(L)} + b^{(L+1)}$  and overall function is a compo:  $g = f \circ f^{(L)} \circ \dots \circ f^{(2)} \circ f^{(1)}$

**Goal:** Compute for all  $(i, j, l): \frac{\partial \mathcal{L}}{\partial w_{ij}^{(l)}}$  and  $\frac{\partial \mathcal{L}}{\partial b_j^{(l)}}$ . **FW pass:** set  $x^{(0)} = x_n$ , then compute  $z^{(1)}$  and  $x^{(1)}$   $\mathcal{O}(K^2 L)$

**BW pass:** Define  $\delta_s^{(l)} = \frac{\partial \mathcal{L}}{\partial z_s^{(l)}} = (W^{(l+1)})^T \delta^{(l+1)} \odot \phi'(z^{(l)})$   $\rightarrow$  Initialize by  $\delta = z - y_n$  (MSE!)  $\mathcal{O}(K^2 L)$

$\Rightarrow \frac{\partial \mathcal{L}}{\partial b_j^{(l)}} = \delta_j^{(l)}$   $\frac{\partial \mathcal{L}}{\partial w_{ij}^{(l)}} = \delta_j^{(l)} x_i^{(l-1)}$  **Issues with GD:** Grad Vanishing or exploding. Solutions are:

1) **Param initialization:** Control layerwise Var of the neurons (He!)  $z^{(l)} \sim \mathcal{N}(0, I_K)$   $w_i^{(l+1)} \sim \mathcal{N}(0, \sigma^2 I_K)$   $z^{(l+1)} = \text{ReLU}(z^{(l)})^T w^{(l+1)}$   
 $\sigma^2 = 2K$  for Var  $(z_i^{(l+1)})^2 < 1$

2) **Batchnorm:**  $\hat{z}_n^{(l)} = (z_n^{(l)} - \mu_n^{(l)}) / \sqrt{\sigma_n^{(l)2} + \epsilon}$   $\mu_n^{(l)} = \frac{1}{n} \sum z_n^{(l)}$   $\sigma_n^{(l)2} = \frac{1}{n} \sum (z_n^{(l)} - \mu_n^{(l)})^2 + \epsilon$  **Layer norm:**  $\hat{z}_n^{(l)} = (z_n^{(l)} - \mu_n^{(l)}) / \sqrt{\sigma_n^{(l)2} + \epsilon}$  **than same**

**CNN:** Conv: filter  $f$ , size  $K$ , stride  $S$ .  $x_{n,m}^{(l)} = \sum_{k,l=0}^{K-1} f_{k,l} \cdot x_{n+S\cdot k, m+S\cdot l}^{(l-1)}$   
 $\Rightarrow$  Same filter used  $\rightarrow$  weight sharing. Value depends on close values.  
 $\Rightarrow$  0 and valid padding. Can also use multiple filters.  $(\text{kernel} = \frac{W_{in} + 2P - F}{S})$

**Conv layer** has multiple filters. HP: size, padding, stride  
**Pooling:** Max or Avg  $\rightarrow$  reduce spatial dim. HP: size, type, stride  
 ReLU after each conv layer to make it non-linear.

**Backprop:** 1) Backpropa:  $\text{ndep}$  2) Sum grad of edges with same weights  
**ResNet:** Add  $x$  to standard Network  $f(x)$   $\rightarrow$  skip-connection  $R(x) + x$

**Data augmentation:** transform  $\gamma: \mathbb{R}^d \rightarrow \mathbb{R}^d$  (same label) by rotation  
**Weight decay:**  $\min \mathcal{L} + \frac{\lambda}{2} \sum \|W^{(l)}\|^2$  No need for Bias.  
**Dropout:** Subnetwork by keeping with proba  $p$  each node. But use whole network when testing.

**Adversarial ML:** Standard vs Adv risk:  $R(f) = \mathbb{E}_{\mathcal{D}} [L(f, X, Y)]$ ,  $R_A(f) = \mathbb{E}_{\mathcal{D}} [\max_{x, y: x \sim \mathcal{D}_X, y \sim \mathcal{D}_Y} L(f, x, y)]$

**Generational adv example:** given input  $(x, y)$  and  $f: X \rightarrow \{1, 2, 3\}$ . Find  $X^*$  st:  
 a)  $\|x - x^*\| \leq \epsilon$  b) the model  $f$  makes a mistake  $\Rightarrow \max_{x: \|x - x^*\| \leq \epsilon} L(f, x, y)$

**Issues:** 1)  $L$  not continuous 2) NN pred output  $\{1, 2, 3\}$ . **Solutions:** 1) use  $\text{softmax}$ :  $g(x) = \frac{e^{f(x)}}{\sum e^{f(x)}}$   
 2) Consider output before classif  $(f(x) = \text{sign}(g(x)))$ .  $P(y = 1|x)$

$\Rightarrow$  **White-box:** Solve  $\max_{x: \|x - x^*\| \leq \epsilon} \mathcal{L}(f, g(x))$   $\nabla_x \mathcal{L}(f, g(x)) \nabla_x g(x) (\alpha - \gamma \nabla_x g(x))$   
 $\leq 0$  since classification loss are decreasing

**L2:**  $\hat{x} = x - \epsilon y$   $\nabla_x \mathcal{L}(f, g(x))$  **Loo:**  $\hat{x} = x - \epsilon y \cdot \text{sign}(\nabla_x \mathcal{L}(f, g(x)))$   $\rightarrow$  PGD: multiple steps!  
 don't know  $g(x)$

**Black-box:** a) score-based: query conti. model scores  $g(x)$  but needs lots of queries  
 $\nabla_x g(x) \approx \sum_{i=1}^d \frac{g(x + \epsilon e_i) - g(x - \epsilon e_i)}{2\epsilon} e_i$  b) Decision-based: query only predicted class  $\hat{f}(x) \in \{1, 2, 3\}$

**Transfer attacks:** Train  $f$  on similar data  $\Rightarrow$  model stealing

**Train robust models:** Train and min on adv examples and risk.  
 $\Rightarrow \min_{\theta} \frac{1}{n} \sum_{i=1}^n \max_{x, y: x \sim \mathcal{D}_X, y \sim \mathcal{D}_Y} \mathcal{L}(y, g_{\theta}(x_i))$   
 1) approx  $\hat{x}_i^* \approx \arg \max_{x: \|x - x_i\| \leq \epsilon} \mathcal{L}(y, g_{\theta}(x_i))$  with PGD  
 2) GD w.r.t  $\theta$  using  $\frac{1}{n} \sum_{i=1}^n \nabla_{\theta} \mathcal{L}(y, g_{\theta}(\hat{x}_i^*))$

**Note:** robustness comes at the cost of accuracy

**Matrix factor:**  $X (d \times n) \approx W Z^T, W \in (d \times k)$  from (row),  $Z \in (n \times k)$  user (row),  $k \ll n$   
 $\Rightarrow \min_{W, Z} \sum_{i=1}^n \|x_i - (Wz_i)^T\|_2^2 \Rightarrow$  opt. not jointly convex and not unique

**K: # latent feat. large  $K \rightarrow$  overfit** Res:  $\|W, Z\|_F^2 + \frac{\lambda}{2} \|W\|_F^2 + \frac{\lambda}{2} \|Z\|_F^2$   
 $(\text{HAT})_F^2 = \sum_{i=1}^n \sum_{j=1}^k a_{ij}^2$  **SGD:** Derive  $\nabla$  for  $(d, k)$   $(W), (n, k)$   $(Z)$  for fixed  $(d, n)$ .

**ALS:** Assume  $X$  is full, we use coord descent:  $\text{Cost } \mathcal{O}(K)$  indep of  $N, d$ !  
 $\min_{W, Z} \sum_{i=1}^n \|x_i - (Wz_i)^T\|_2^2 \Rightarrow$  fix  $W$  min  $Z$ , vice-versa  
 $\Rightarrow Z^* = (W^T W + \lambda I_k)^{-1} W^T X$   $W^* = (Z^T Z + \lambda I_d)^{-1} Z^T X$   $\rightarrow$  optimal  $\text{Cost } \mathcal{O}(dKn + k^2)$ !

$\Rightarrow$  But  $X$  not full.  $\min_{W, Z} \sum_{i=1}^n \|x_i - (Wz_i)^T\|_2^2 \Rightarrow 1) \nabla_W \mathcal{L}(W, Z) = 0$  2)  $\nabla_Z \mathcal{L} = 0$ ...

**Text represent:** find  $w_i \rightarrow W_i \in \mathbb{R}^K$  Words  $\rightarrow$  features **Co-occur matrix:**  
 $n_{ij}$  = # contexts where  $w_i$  occurs with  $w_j$ . very sparse  $d \times n$ . Need context (size) and Vec  $\rightarrow$

**Matrix factor:** log of counts:  $X_{ij} = \log(n_{ij}) \rightarrow X \approx WZ^T$  where  $W$  (word),  $Z$  (context word)  
 $\min_{W, Z} \sum_{i,j} \|x_{ij} - (Wz_j)^T\|_2^2$  **Glove:**  $f_{ij} = \min \{l_i, r_j, \min(n_{ij}, n_{max})\}$ ,  $\alpha \in [0, 1]$

**Training w/ SGD or ALS:**  $\mathcal{O}(K)$  per step **SKIP-gram (Word2vec):** use log-vec to separate real word pairs  $(w_d, w_0)$  from fake ones. (real: appearing in context window's)

**Fast text:** Supervised:  $S_n = (w_1, \dots, w_n)$  and  $x_n \in \mathbb{R}^K$ . Both of  $S_n$  and  $y_n \in \{1, 2, 3\}$  label:  
 $\min_{W, Z} \sum_{n=1}^N \|x_n - \sum_{i=1}^n f(y_n, WZ^T x_n)\|_2^2, W \in \mathbb{R}^K, Z \in \mathbb{R}^{K \times K}$ ,  $f$  a classifier

Supervised: use CNN or ml fact **unsupervised:** adding or avg word vectors and train, then direct unsupervised train using sentences instead of words.

**LLMs: gLM:** distribution over text:  $p(l \text{ saw a cat on a mat}) = p(x_1, \dots, x_n)$  Next-token pred:  
 $P(x_1 | x_2, \dots, x_n) = P(x_1 | x_2, \dots, x_n) \rightarrow P(x_1) = p(\text{mat} | \text{saw a cat on a}) = 0.002$

**Tokenizer:** indep from model **AR inference:** 1) tokenize 2) forward 3) proba for next token  
 4) sample 5) detoken  $\rightarrow$  2) **Data pretraining:** A lot of low quality to learn.

**Post-training:** small or high quality to make model usable. **Distributed learning:**  
 Use need multiple GPUs to run in parallel 3) **Posttraining:** zs vs ps (in-context): if we give examples to GPT, it will perform better. Also: if we give examples of reasoning (CoT). **Supervised finetuning:** Have labels show desired output

**Linear:**  $L(x) = \theta^T x$  (Learned) **Non-linear:**  $f(x) = \phi(W^T x + b)$  (Learned) **Hidden layers:**  $d$  inputs  $K$  neurons  $W$  matrices  $b$  vectors

Outputs of hidden layer  $l$  given by vector:  $x^{(l)} = f^{(l)}(x^{(l-1)}) := \phi((W^{(l)})^T x^{(l-1)} + b^{(l)})$

**Representation power:** We can use sigmoids to approximate functions. Gross:  $(x_1, x_2) \rightarrow \phi(w_1(x_1 - a_1)) - \phi(w_2(x_2 - b_1)) + \phi(w_3(x_2 - a_2)) - \phi(w_4(x_2 - b_2))$

**USE:**  $\min_{w_1, w_2} \int_{x_1, x_2} (f(x) - g(x))^2 dx \leq \frac{C}{n}$  Also use comb of ReLU as PNL

**SGD:**  $(w_{ij}^{(l)})_{t+1} = (w_{ij}^{(l)})_t - \gamma \frac{\partial \mathcal{L}}{\partial w_{ij}^{(l)}}$   $(b^{(l)})_{t+1} = (b^{(l)})_t - \gamma \frac{\partial \mathcal{L}}{\partial b^{(l)}}$  But doing all chain rules too expensive. **Solution: Backpropagation.**

**NN Params:**  $W^{(l)}: d \times K, W^{(L)}: K \times K$  for  $1 \leq l \leq L, W: K \times K, b^{(l)}: K \times 1$  for  $1 \leq l \leq L, b: K \times 1$   $x^{(l)} = f^{(l)}(x^{(l-1)}) := \phi((W^{(l)})^T x^{(l-1)} + b^{(l)}) = \phi(z^{(l)})$

$\Rightarrow$  Final layer  $y = f^{(L+1)}(x^{(L)}) := (W^{(L+1)})^T x^{(L)} + b^{(L+1)}$  and overall function is a compo:  $g = f \circ f^{(L)} \circ \dots \circ f^{(2)} \circ f^{(1)}$

**Goal:** Compute for all  $(i, j, l): \frac{\partial \mathcal{L}}{\partial w_{ij}^{(l)}}$  and  $\frac{\partial \mathcal{L}}{\partial b_j^{(l)}}$ . **FW pass:** set  $x^{(0)} = x_n$ , then compute  $z^{(1)}$  and  $x^{(1)}$   $\mathcal{O}(K^2 L)$

**BW pass:** Define  $\delta_s^{(l)} = \frac{\partial \mathcal{L}}{\partial z_s^{(l)}} = (W^{(l+1)})^T \delta^{(l+1)} \odot \phi'(z^{(l)})$   $\rightarrow$  Initialize by  $\delta = z - y_n$  (MSE!)  $\mathcal{O}(K^2 L)$

$\Rightarrow \frac{\partial \mathcal{L}}{\partial b_j^{(l)}} = \delta_j^{(l)}$   $\frac{\partial \mathcal{L}}{\partial w_{ij}^{(l)}} = \delta_j^{(l)} x_i^{(l-1)}$  **Issues with GD:** Grad Vanishing or exploding. Solutions are:

1) **Param initialization:** Control layerwise Var of the neurons (He!)  $z^{(l)} \sim \mathcal{N}(0, I_K)$   $w_i^{(l+1)} \sim \mathcal{N}(0, \sigma^2 I_K)$   $z^{(l+1)} = \text{ReLU}(z^{(l)})^T w^{(l+1)}$   
 $\sigma^2 = 2K$  for Var  $(z_i^{(l+1)})^2 < 1$

2) **Batchnorm:**  $\hat{z}_n^{(l)} = (z_n^{(l)} - \mu_n^{(l)}) / \sqrt{\sigma_n^{(l)2} + \epsilon}$   $\mu_n^{(l)} = \frac{1}{n} \sum z_n^{(l)}$   $\sigma_n^{(l)2} = \frac{1}{n} \sum (z_n^{(l)} - \mu_n^{(l)})^2 + \epsilon$  **Layer norm:**  $\hat{z}_n^{(l)} = (z_n^{(l)} - \mu_n^{(l)}) / \sqrt{\sigma_n^{(l)2} + \epsilon}$  **than same**

**Transformers:**  $f: \text{seq} \rightarrow \text{seq}$  input (T) **token**  $\rightarrow$  tokens of dim  $D$  **trance**  $T \times b \rightarrow$  output **Transformer:** LU, SA (between), MLP (within), SC

**Input:** Tokenized  $\rightarrow$  Embedding: map each token  $t_i$  into vector  $w_i \in \mathbb{R}^D \rightarrow X = [w_0, w_{eos}, \dots, w_{eot}] \in \mathbb{R}^{T \times D}$   
 $W_{emb} = [w_0, \dots, w_{eot}] \in \mathbb{R}^{(T+1) \times D}$  learn via backprop.  $X = [e_1, \dots, e_T] W_{emb}$  **Position:**  $X = [e_1, \dots, e_T] W_{emb} + [p_1, \dots, p_T] W_{pos}$   
 $\Rightarrow$  SA doesn't account for position

**SA:** A: tok  $\rightarrow$  tok using learned indep. weighted avg.  $\Rightarrow z = \text{softmax}(\frac{XW_{SA}}{\sqrt{D}}) XW_V$   $\mathcal{O}(T^2)$   $W_K, W_Q (D \times D), W_U (D \times D)$   
 $\Rightarrow$  can also do it for H SA:  $Z_H$

**MLP:** mix info within each token:  $\text{MLP}(x) = \phi(XW_U)W_O \rightarrow$  applied to each token. **output:** single or multiple (simple)

Transformers are used for Encoders (classification), Decoders (chat GPT), Encoder-decoder (translation)

**Unsupervised learning: Model-Based clustering: K-Means:**  $F: X \rightarrow K$  clusters and find cluster centroids  $\mu_k$  and Assignment  $Z \in \mathbb{R}^{n \times K}$

**Objective function:**  $\min_{\mu, Z} \sum_{n=1}^n \sum_{k=1}^K z_{nk} \|x_n - \mu_k\|_2^2$  s.t.  $\mu_k \in \mathbb{R}^D, z_{nk} \in \{0, 1\}, \sum_{k=1}^K z_{nk} = 1$  (WCSS)  $W$ : Within

**Algo:** 1) input data  $D$ , # clusters  $K$  2) Initialize random  $\mu_k$  3) Assign each point to new center  $z_{nk} = \arg \min_k \|x_n - \mu_k\|_2^2$   $z_{nk} = 0$  other wise  
 4) update centroids (means):  $\mu_k = \frac{\sum_{n=1}^n z_{nk} x_n}{\sum_{n=1}^n z_{nk}}$   $\Rightarrow$  repeat 3) 4) until convergence **Iteration cost**  $\mathcal{O}(NKd)$   $\rightarrow$  the WCSS

**Convergence: coordinate descent:**  $z^{(t+1)} = \arg \min_z \mathcal{L}(z, \mu^{(t)})$   $\mu^{(t+1)} = \arg \min_{\mu} \mathcal{L}(z^{(t+1)}, \mu)$   $\rightarrow$  optimum not guaranteed

**Challenges:** 1) depends on initialization  $\Rightarrow$  K-means++: spread initial centroids  $\mathcal{O}(\log K)$  optimal solution  
 2) Which  $K$  optimal?  $\rightarrow$  Elbow method of  $K$  on WCSS. 3) Can't model other shapes than spheres. 4) sensitive to outliers  
 5) Hard assignments in overlapping clusters.

**GMM:** Calculate distribo of clusters.  $K$  Gaussians.  $Z$  (unobserved) multinomial  $\rightarrow P(z = k) = \pi_k \rightarrow z_k \pi_k = 1$

**MLE:**  $\max_{\mu, \sigma, \pi} \log(\sum_{k=1}^K \pi_k \mathcal{N}(x_n | \mu_k, \sigma_k^2))$  but Non-convex, no unique Opt, unbounded.  $\Rightarrow$  need EM algorithm

**Hard EM:**  $\theta^{(t)} = \{ \pi_k, \mu_k, \sigma_k^2 \}_{k=1}^K$   $\in \mathbb{E}$ : Predict most likely class for each data point:  $z_n^{(t)} = \arg \max_k \pi_k \mathcal{N}(x_n | \mu_k, \sigma_k^2)$   $\rightarrow$  labeled data!  
 $\mu_k^{(t)} = \frac{\sum_{n=1}^n z_{nk} x_n}{\sum_{n=1}^n z_{nk}}$   $\sigma_k^{(t)2} = \frac{\sum_{n=1}^n z_{nk} \|x_n - \mu_k^{(t)}\|_2^2}{\sum_{n=1}^n z_{nk}}$   $\pi_k^{(t)} = \frac{\sum_{n=1}^n z_{nk}}{n}$  **Iteration cost**  $\mathcal{O}(NKd^2)$

**Soft EM:** use posteriors  $\theta^{(t)} = \{ \pi_k, \mu_k, \sigma_k^2 \}_{k=1}^K$   $\in \mathbb{E}$ : Compute posteriors:  $q_k^{(t)}(x_n) = p(z_n = k | x_n, \theta^{(t-1)}) = \frac{\pi_k \mathcal{N}(x_n | \mu_k, \sigma_k^2)}{\sum_{l=1}^K \pi_l \mathcal{N}(x_n | \mu_l, \sigma_l^2)}$

**MLE of  $\theta$  using  $q_k^{(t)}(x_n)$ :**  $\mu_k^{(t)} = \frac{1}{N} \sum_{n=1}^n q_k^{(t)}(x_n) x_n$ ,  $\sigma_k^{(t)2} = \frac{\sum_{n=1}^n q_k^{(t)}(x_n) \|x_n - \mu_k^{(t)}\|_2^2}{\sum_{n=1}^n q_k^{(t)}(x_n)}$ ,  $\pi_k^{(t)} = \frac{\sum_{n=1}^n q_k^{(t)}(x_n)}{N}$  **Iteration cost**  $\mathcal{O}(NKd^2)$

**General EM:** Not only GMM:  $\mathcal{L}(\theta) = \mathcal{L}(q, \theta) + \mathcal{KL}(q || P)$  where  $q$  is distribution  $q(z)$  s.t.  $Z \sim q(z)$   $\rightarrow$  coordinate ascent algorithm or  $\mathcal{L}(q, \theta)$

**Goal:** Max incomplete  $\mathcal{L}(\theta) = \log(P(x|\theta))$  by max lower bound:  $\mathcal{L}(q, \theta) = \log \frac{P(x, z|\theta)}{q(z)}$

**E:** Compute  $P(z | x, \theta^{(t)})$ :  $q^{(t+1)} = \arg \max_q \mathcal{L}(q, \theta^{(t)})$ . Write  $\log p(X, Z | \theta)$  and calculate:  $\mathbb{E}_Z [\log p(X, Z | \theta) | X, \theta^{(t)}]$

**M:** Max  $\theta^{(t+1)} = \arg \max_{\theta} \mathbb{E}_Z [\log p(X, Z | \theta) | X, \theta^{(t)}] \Rightarrow \theta^{(t+1)} = \arg \max_{\theta} \mathcal{L}(q^{(t+1)}, \theta)$  **Note:**  $\mathcal{L}(\theta^{(t+1)}) \geq \mathcal{L}(q^{(t)}, \theta^{(t)}) \geq \mathcal{L}(q^{(t)}, \theta^{(t)}) \geq \mathcal{L}(\theta^{(t)})$

alternately computing a lower bound on the log likelihood for the current parameter values (E) and then maximizing this bound to obtain the new parameter values (M)

**Initialization:** Weights: uniform Means: Rand or K-Means++ Var: empirical

**Self-supervised:** uses input data to create label or tasks  $\Rightarrow g: X \rightarrow \phi(x, x_{adj})$  then learn  $f: x_{in} \rightarrow x_{out}$  (e.g. MLM)

**MLM:** learn to predict hidden words. BERT: finds Masked words, learn order of the sentence and classifies.

**Joint embed. methods:** Rather than  $f: x_{in} \rightarrow x_{out}$ , learn  $f: x \rightarrow \mathbb{R}^d$  s.t.  $f(x_i) \approx f(x_j)$  **Problem:** constant  $f$ . **Solution:** BYOL:  $f_1(x_i) \approx f_2(x_j)$  and Contrastive learning: similarity or  $\otimes$  example pair better than  $w \otimes = \langle f(x), f(x') \rangle > \langle f(x), f(x'') \rangle$

**SimCLR:** 1. Classifies  $L(x) = -\log \frac{\exp(\langle f(x), f(x') \rangle)}{\sum_{x''} \exp(\langle f(x), f(x'') \rangle)}$  2. Map encoder output to similarity space:  $f(x_1) = f_2 = f_1(x)$   $f_2$  projector

3. cosine similarity:  $\langle e_1, e_2 \rangle = \frac{\langle e_1, e_2 \rangle}{\|e_1\| \|e_2\|} / \gamma$   $\rightarrow$  data augmentation **CLIP:** Max similarity of captions and images

**Gen Models:** instead of model  $P(y|x)$ , model  $P(x)$ . **Explicit:** model prob distribo of  $x$  **Implicit:** generate samples according to it

**GAN:** Generator  $G(\theta)$ , Discriminator  $D(\phi)$ .  $D$  judges what  $G$  produces.  $\theta = \arg \min_{\theta} \mathcal{L}^D(\theta, \phi)$   $\phi = \arg \min_{\phi} \mathcal{L}^D(\theta, \phi)$

1)  $D$  distinguishes real vs. fake sample. 2)  $G$  wants to fool  $D$ . 3. **obj:**  $\min_{\theta} \max_{\phi} \mathbb{E}_{x \sim p} [\log D(x)] + \mathbb{E}_{z \sim \mathcal{N}} [\log (1 - D(G(z)))]$  **Losses:**  
 $\mathcal{L}_G(G, D) = \max_{\phi} \mathbb{E} [\log D(x)] + \mathbb{E} [\log (1 - D(G(z)))]$   $\mathcal{L}_D(G, D) = \min_{\theta} \mathbb{E} [\log (1 - D(G(z)))]$  4. **opt solution:**  $\theta_g = \theta_d = -\log 1/2$  **CGAN:** Condition

**Diff models:** add noise and train model to recover the data. Consider a MC with  $x_0 \sim p_0$  and forward transition such that  $x_{t+1} \sim P(x_{t+1} | x_t)$ . **Forward decomps:**  $p(x_0, x_T) = p_0(x_0) \prod_{t=0}^{T-1} p(x_{t+1} | x_t)$  where at each step, the marginal satisfies  $p(x_t) = \int p(x_{t+1} | x_t) p(x_t) dx_{t+1}$ . Using bayes  $p(x_t | x_{t+1}) = p(x_{t+1} | x_t) p(x_t) / p(x_{t+1}) \Rightarrow p(x_{0:T}) = p_T(x_T) \prod_{t=0}^{T-1} p_t(x_t | x_{t+1})$  **Backward!**

**We use ancestral sampling:** Sample  $X_T \sim p_T(\cdot)$  then: for  $k = T-1, \dots, 0$ : Sample  $X_k \sim p_k(\cdot | x_{k+1})$

$p_0 = p_{data} \in \mathcal{P}(\mathbb{R}^d)$  | forward transition:  $P(x_{t+1} | x_t) = \mathcal{N}(x_{t+1}; \mu_t, (\sigma_t^2) I_d)$  |  $P(x_t | x_{t+1}) = \mathcal{N}(x_t; \mu_t', (\sigma_t'^2) I_d)$  | MC converges to  $\text{trac} = \mathcal{N}(x; \theta, \Sigma)$  for  $T \rightarrow \infty \Rightarrow$  for  $T$  large enough:  $P(x_t) \approx \text{trac}(x)$ . **Problem:** BW transition  $P(x_t | x_{t+1})$  needs to be approx  $\Rightarrow p(x_t | x_{t+1}) = p(x_{t+1} | x_t) \exp[\log p(x_t) - \log p(x_{t+1})] \approx \mathcal{N}(x_t; (2 - \alpha) x_{t+1} + (1 - \alpha)^2 \nabla \log p(x_{t+1}), (1 - \alpha^2) I_d)$

Approximate score with a NN:  $\theta^* = \arg \min_{\theta} \frac{1}{2} \sum_{t=1}^T \mathbb{E}_{x_t \sim p_t} \|s_{\theta}(t, x_t) - \nabla \log p(x_t | x_0)\|^2$  **Score**